# **Description**

The HRL incremental encoder fits onto an existing shaft and converts shaft rotation into square wave pulses to provide an accurate and reliable means of digitizing position, rate, or length of travel. The number of pulses per shaft revolution is determined by setting configuration switches.

# **Model ID**

<u>HRL</u> \_--<u>P436AJ</u>/\_\_

Shaft diameter:  $\underline{1} = 1''$ 

Supply voltage:

5 or <u>8-30</u>

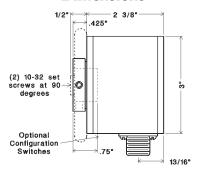
M25 = 25mm (Inquire for others)

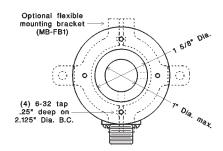
Short lead time options are underlined.

### Installation

- 1. Slide HRL onto shaft.
- 2. Fasten flexible mounting bracket (MB-FB1) to frame, or use other means to prevent rotation.
- Tighten HRL shaft set screws.
- 4. Attach the cable leads to the control device (e.g. PLC) ensuring that the power supply meets specifications.
- 5. Set the configuration switches (can be changed at any time).
- 6. Attach the cable to the encoder.

### **Dimensions**







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## **Specifications**

#### **Electrical**

Supply Voltage (V<sub>IN</sub>): (see Model ID)

5 ± 5% vdc8 to 30 vdc

Supply Current: 50ma maximum (no load)

Output Current (Io): 50ma max source/sink

Output Circuit: Selectable by setting switches 6 to 8 (see figures 1 and 2)

- Current sinking NPN transistor
- Open collector (V<sub>CC</sub>=30 vdc max)
- Current sourcing PNP transistor
- Combined sourcing/sinking output (push/pull output)

**Operating temperature:** 0° to 70° C **Maximum operating speed:** 1,500 rpm

## Outputs

**Pulses per Revolution:** Selectable by setting switches 1 to 5 (see figure 1)

Output Waveform: 50/50 squarewave

- Pulse On-Off Ratio:  $50\% \pm 10\%$
- Pulse Interval Jitter: ±10%
- Pulse rise time: 2 μsec (max)
- **Pulse fall time:** 5 μsec (max)
- Voltage (high): V<sub>in</sub>-2.5 vdc (min)Voltage (low): 1.5 vdc (max)

(600 rpm, V<sub>IN</sub>=24vdc, 10ma<I<sub>O</sub><50ma, 25°C)

Anti-Jitter: The anti-jitter feature increases the pulse output hysteresis to ½ of a pulse width, eliminating the effects of mechanical vibration and the possible dither that results in false output pulses. For example, a 10 pulse per revolution output would have 18° hysteresis (i.e. 360° ÷ 10 × ½).

### Mechanical

Weight: 16.8 oz (477 gm) without cable

Bearing Loading: 25 lb. radial (max)

10 lb. axial (max)

**Bearing Life (L<sub>10</sub>):**  $36 \times 10^6$ /RPM = hours

Materials:

— Case: 1/4" Aluminum, anodized

— Shaft: Aluminum

- Window: Plastic

#### **Electrical Connections**

Pin No.	Function	Wire Color
Α	Supply Voltage	Red
В	Common	Black
С	Output	White
D	no connection	
E	no connection	
	Case Ground	Plain

**Connector:** MS3102A-14S-5P (5-pin) **Mating Connector:** MS3106A-14S-5S

#### Accessories

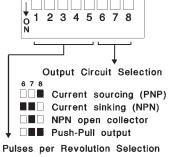
Cable Assembly (C5-3-10): 10 ft. (3m) of 5 conductor, shielded cable with mating connector. Other lengths are available.

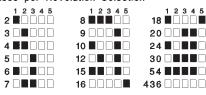
CE mark requires Photocraft cable, and surge protection if the cable exceeds 100′ (30m) or leaves the building.

#### Flexible Mounting Brackets:

flexible stainless steel that allows for axial and angular shaft misalignment. Call or see our website for more details.

### **Configuration Switches**

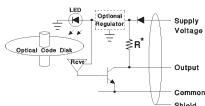




Switch definitions:  $\square$  Up (off),  $\blacksquare$  Down (on).

Figure 1 - Configuration Switches





\*R is removed for NPN open collector

Optional Regulator Voltage

Regulator Output

R Common Shield

Current Sourcing

(PNP Output)

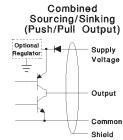


Figure 2 - Output Circuits